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You can find in the file:
m682.dat,
post-processed and calibrated
1 minute temporal values
from the DVS-database.
no value / error value: -999.0
Variables [Units]:
 1. date dd,
 2. date mm,
 3. date yyyy,
 4. time hh,
 5. time mm,
 6. time ss,
 7. julian days [ days since 2006/01/01, where 1st jan is day 1 ],
 8. latitude [ decimal degrees north ],
    Device: GPS
 9. longitude [ decimal degrees east ],
    Device: GPS
 10.true windspeed [ m/s ],
    Windspeed was measured by two heated cup anemometers at 40.1 m
    above sea level on port and starport side. Relative wind was
    converted to absolute wind using ships heading and speed. The
    luv sensor data is included in this dataset.
 11.true wind direction [ degrees ],
    Wind direction was measured by two vanes at 40.1 m above sea
    level on port and starport side. Relative wind was converted
    to absolute wind using ships heading and speed. The luv sensor
    data is included in this dataset.
 11.air pressure [ hPa ],
    Manufacturer: AIR, type DB-1A
    Location of measurements: 10.6 m, above sea level
 13.air temperature [ degrees C ],
    Device: PT 100
    Location of measurements: 28.3 m above sea level
 14.humidity [ % ],
    Relative humidity was measured by two sensors at 28.3 m above sea
    level, one on port and one on starport side. After calibration of
    the sensors, the luv sensor is included in the dataset.
    Device: capacitive humidity sensors
    Manufacturer: Rotronic
 15.UV radiation [mW/m^2],
    measured by a radiometer, cardanically fitted to equilibriate ship movement
    relative to horizontal. The instrument was built by
    Meteorologisches Observatorium Potsdam (DWD)
    Device Type: UV-S-EA-T
    Location of measurements: 40.1 m above sea level, mid-ship
 16.SST [ degrees C ],
    Sea surface temperature was continously measured by a
    thermosalinograph sampling water from a depth of 1.5 m
    below the vessel's waterline. The temperature sensor was
    calibrated against on-station temperature and conductivity
    values from CTD-profiles.
    Device: Seacat SBE 21
    Manufacturer: SEA-Bird Electronics, Inc.
 17.SSS [ p.s.u. ],
    Sea surface salinity was continously measured by a
    thermosalinograph sampling water from a depth of 1.5 m
    below the vessel's waterline. The conductivity sensor was
    calibrated against on-station conductivity and temperature
    values from CTD-profiles.
    Device: Seacat SBE 21
    Manufacturer: SEA-Bird Electronics, Inc.
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